

Dual Log sounder Interface firmware development

- V1.7 NO COMPATIBLE PROCESSOR
 - Improving the functioning of the depth finder in the small waters
 - Manual setting of the depth finder blanking to avoid keel echo.
- V2.0 PROCESSOR COMPATIBLE

Warning:

For the I2LS built before July 2010, a hardware modification is necessary.

THE ULTRASONIC SPEEDO SENSORS MUST BE DIFFERENTIATED "PORT" AND "STARBOARD" (See ultrasonic speedo port firmware and Ultrasonic speedo starboard firmware). The connection of 2 speedos running with the same firmware can cause a conflict on the Topline bus

- When a Processor is functioning on the Topline bus, only the depth channel is displayed.
 - When a Processor is functioning on the Topline bus, connect directly on the I2LS one port Ultrasonic speedo sensor and one starboard Ultrasonic speedo sensor (see specifics firmwares for these sensors).
 - Without PROCESSOR, the functioning is the same as the previous version.
- V2.1 PROCESSOR COMPATIBLE
 - Change to keep in memory the 'speed over ground' option after initialization.